

Extensible Conditional Privacy Protection Authentication Scheme for Secure Vehicular Networks in a Multi-Cloud Environment

Jie Cui, Xiaoyu Zhang, Hong Zhong, Jing Zhang, Lu Liu

Abstract—With an increasing number of cloud service providers (CSPs), research works on multi-cloud environments to provide solutions to avoid vendor lock-in and deal with the single-point failure problem have expanded considerably. However, a few schemes focus on the conditional privacy protection authentication of vehicular networks under a multi-cloud environment. In this regard, we propose a robust and extensible authentication scheme for vehicular networks to fulfil the ever-growing diversified service demands from users. According to our solution, the vehicles need to register with the trusted authority (TA) only once to achieve a fast and efficient authentication with CSPs. Additionally, as long as the new CSP is successfully registered in TA, it can participate in vehicular service. A cloud broker, which is managed by the TA, is responsible for connecting all the cloud services; consequently, the complexity involved in the selection of CSPs is hidden from the users' view. A detailed security analysis establishes that our scheme can fulfil conditional privacy protection and achieve the security objectives of vehicular networks. Our scheme is based on elliptic curve cryptography and does not employ the complex bilinear pairing operation. An evaluation of performance of the proposed scheme indicates that it is suitable for applications involving vehicular networks.

Index Terms—Vehicular networks, multi-cloud environment, authentication, elliptic curve

I. INTRODUCTION

As an indispensable part of the Internet of Things, vehicular networks play an ever-increasing important role in our daily life. Vehicular networks are employed by the vehicles with the aid of advanced on-board units that demonstrate excellent sensing, communication, and network functions to communicate with neighboring vehicles or infrastructure for achieving two primary applications [1]. Firstly, the vehicular network ensures safety by providing the drivers with information on road conditions and traffic conditions to improve the traffic efficiency. Secondly, it delivers infotainment by providing the users with map downloads, online entertainment information, and other services to enhance the driving experience and travel pleasure [2].

Although vehicular networks present significant advantages in our everyday life, there are several challenges in achieving their large-scale deployment. First, vehicular communication

in a wireless environment is vulnerable to malicious attacks by adversaries, which can cause the information be intercepted, forged, or tampered with [3]. It is, therefore, important to ensure the privacy and integrity of the messages [4]. Second, the explosive increase in the number of vehicles and the diversified demands for new vehicular services require the researchers to critically explore relevant novel solutions in this field [5].

Some researchers have proposed the concept of vehicular clouds. A vehicular cloud is a temporary cloud that comprises many volunteer vehicles [1], [6]. Although this approach of building a cloud exploits the redundant power of vehicles and expands the computing, processing, and storage capabilities of traditional clouds to some extent, some unresolved problems still persist. For instance, there is no specific tactic to effectively select the relay vehicles. Moreover, this approach results in new security and privacy risks. For example, intermittent short-range communication in high-dynamic network environments can pose difficulties in providing a reliable commitment to the computation-intensive and delay-sensitive applications [7].

Therefore, optimizing and expanding the traditional vehicular cloud architecture demonstrates greater practical significance [8]. Nevertheless, simply adopting the previous vehicles and the single cloud service provider (CSP) mutual authentication scheme under the new situation is impossible mainly because they do not consider the need for users to switch and choose among multiple cloud service providers [9], [10]. Therefore, in this study, we consider the authentication scheme of vehicular networks in a multi-cloud environment. The term “multi-cloud” signifies different cloud services provided by multiple CSPs. Multi-cloud is essentially a strategy rather than a technology [11]. Studies on this strategy have been increasingly prevalent in recent times [12]. The key reason is that it not only provides users with more flexible choices and highly diverse services but also prevents the vendor lock-in and risk of a single-point failure [8].

Meanwhile, the users encounter difficulties in effectively considering one appropriate CSP due to the emergence of several service providers [13]. To address this problem, we use the cloud broker (CB), which refers to an entity that manages the application, performance, and delivery of the cloud services [14]. And according to the National Institute for Standards and Technology (NIST), cloud brokering services are mapped into three general areas: service intermediation, service aggregation and service arbitrage [15], [16]. In our scheme, CB mainly manages the negotiation between the CSPs

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and vehicles by acting as an intermediary for providing users with superior service experience [17].

The aforementioned analysis signifies the importance of studying the authentication scheme of vehicular networks over multi-cloud environments. Therefore, in this study, we present an extensible conditional privacy protection authentication scheme based on the proposed novel vehicular network model in a multi-cloud environment. It is worth mentioning that this scheme is suitable for the 3G, 4G, and emerging 5G networks environments, as it does not require the roadside base stations to participate in the authentication process.

A. Our Motivations

Firstly, references [18] and [19] make us realize that the research on a multi-cloud environment is important and of great practical significance. Secondly, the existing research on mobile phones and mobile medical devices in a multi-cloud environment [20], [21], [22], [23] lets us focus on the vehicular networks which is a sub-category of mobile Internet of Things. In addition, the reference [24] mentions that the multi-cloud environment is beneficial to solving server management problems in vehicular networks. All in all, the above references strengthen our determination to study vehicular networks in a multi-cloud environment.

B. Our Contributions

To the best of our knowledge, this is the first authentication scheme for secure vehicular networks in a multi-cloud environment with a CB that acts as an intermediary. The main contributions are summarized as follows:

- We propose a novel vehicular network architecture for a multi-cloud environment. The CB which is managed by the trusted authority (TA) selects appropriate CSPs for vehicles; consequently, the complexity in the selection of CSPs is hidden from the users' view and the dependence of vehicles on a single CSP is eliminated.
- The vehicles and CSPs need to register with the TA only once for mutual authentication and session key agreement. The proposed scheme alleviates the hassle of key management of vehicles and eliminates the trouble of repeated registrations of vehicles with different CSPs. Moreover, it does not require the CSPs to maintain the considerable amount of redundant registration information of vehicles.
- An in-depth security analysis confirms that the proposed scheme can achieve the security objectives of vehicular networks. Furthermore, during the entire authentication phase, the vehicles can remain anonymous to CSPs resulting in better privacy protection. The scheme employs the elliptic curve encryption algorithm, and the comparison results with recent related schemes indicates that it is suitable for deployment in real-world applications.

C. Organization of the Rest Paper

Section II introduces the related work. Section III provides the background knowledge used in this study. In Section IV,

the specific scheme is presented. Then, Section V shows the detailed security proof and analysis. In Section VI is the performance analysis and comparison from the aspects of computation and communication costs. Finally, some concluding remarks is provided in Section VII.

II. RELATED WORK

The increasing number of vehicles and the urgent demands for diversified vehicular services have already motivated the global academic and business community devoted exclusively to introduce novel pragmatic paradigms in the new situation.

In 2010, Olariu *et al.* [6] first proposed the concept of Autonomous Vehicular Cloud (AVC), which means that underutilized autonomous vehicles gather together to form a temporary cloud for dynamically allocating available resources to authorized users.

Later, Bitam *et al.* [25] proposed that integrating traditional permanent clouds with temporary clouds formed by static vehicles. Through the combination of these two sub-modules, vehicular ad hoc network cloud (VANET-Cloud) is constructed to further expand the traditional cloud resources and better satisfy the needs requested by road users.

Bhoi *et al.* [26] also considered that the resources of static vehicles in the parked lots as the data centers, providing storage services for the vehicles, and proposed a new task scheduling policy. However, the proposed system is based only on resources within the vehicles, ignoring the advantages of traditional cloud computing [27].

It is noteworthy that in the above schemes, the entry and departure of vehicles in the parking lot makes the network environment dynamic, so it is very challenging to efficiently assign tasks to vehicles [28].

Recently, Shao *et al.* [29] reduced the computing burden of task-requesting vehicles by outsourcing time-consuming bilinear pairing operations to connected vehicular cloud computing (CVCC) which integrates computing resources from traditional clouds, the roadside units (RSUs) and vehicles with underutilized resources. However, this model poses new challenges, such as data security and computational security, due to it allowing potential malicious vehicles to participate in CVCC, while the solution lacks a clear protocol on how to manage server vehicles that leaving CVCC before finishing the task.

In the scheme of Wang *et al.* [7], a novel dynamic vehicle-based cloudlet relaying scheme was proposed for the first time to alleviate the burden of mobile computing and make a reliable commitment to delay-sensitive applications to a certain extent. However, the scheme does not consider how to select vehicles in the cloudlet to cope with the rapid change of network topology.

According to [30], VANET-based clouds have three main architectural frameworks: vehicular clouds (VCs), vehicles using clouds (VuCs), and hybrid vehicular clouds (HVCs). The mentioned [6], [26] and [25], [29] belong to the first and third types respectively. In addition, through the previous analysis, we can find that even though the above schemes improve the resource utilization rate of idle vehicles and reduce

service response time, there are still a series of problems to be addressed, especially the selection, management and task allocation of participating vehicles [31].

Therefore, we propose a novel vehicular network authentication scheme which can be attributed to the extension of VuCs, the second combination type, in a multi-cloud environment. In fact, multi-cloud has received widespread attention in the past few years [29], [32]. The existing literatures signify that it is imperative to construct a multi-cloud environment under the new situation [33], [34], [35].

We pursue the multi-cloud strategy because of the following advantages of vehicular network deployed in a multi-cloud environment: 1) No longer limited to the limited choices offered by a single CSP, multi-cloud can provide users with more flexible choices. While meeting the upsurge diversified demand of a large number of users, it can avoid vendor lock-in and reduce users' over-dependence on a single CSP [11]; 2) The multi-cloud environments can increase the flexibility of the entire system, reduce the risk of vehicle data loss, and avoid a single-point failure of CSP in the process of vehicle access to the service, which results in service interruption [34].

Meanwhile, in order to cope with the problem of the selection of CSPs caused by multi-cloud environments [13], [35], we also introduce the entity of cloud broker [36]. As an crucial part of the cloud architecture, the main role of cloud broker in this study is reflected in: 1) Enable users to interact through a single interface that connects to multiple CSPs; 2) Concealing the complexity of the selection of CSPs from the perspective of the vehicle users; 3) Manage the use, performance and delivery of cloud services, effectively allocate and manage resources, and negotiate the relationship between CSPs and vehicles [14].

Additionally, considering the unique characteristics of the vehicular networks, existing encryption authentication schemes applied to multi-cloud environments in other fields such as medical care can not be directly applied to the vehicular networks. For instance, highly dynamic network topology and limited computing power of on-board units require the scheme has low time overhead, and because the vehicular networks involves significant property and privacy security, the solution must be able to withstand a variety of common types of attacks and meet the requirement of conditional privacy protection [37], [38]. Therefore, in order to fill this gap, researchers need to devote special attention to this issue.

III. SYSTEM MODEL

In this section, the proposed vehicular network model in a multi-cloud environment along with its system assumptions are introduced firstly. Then we present the specific security objectives.

A. Network Model and Assumptions

Fig. 1 illustrates our system model over a multi-cloud environment. It mainly contains the trusted authority (TA), cloud broker (CB), cloud service providers (CSPs), vehicles,

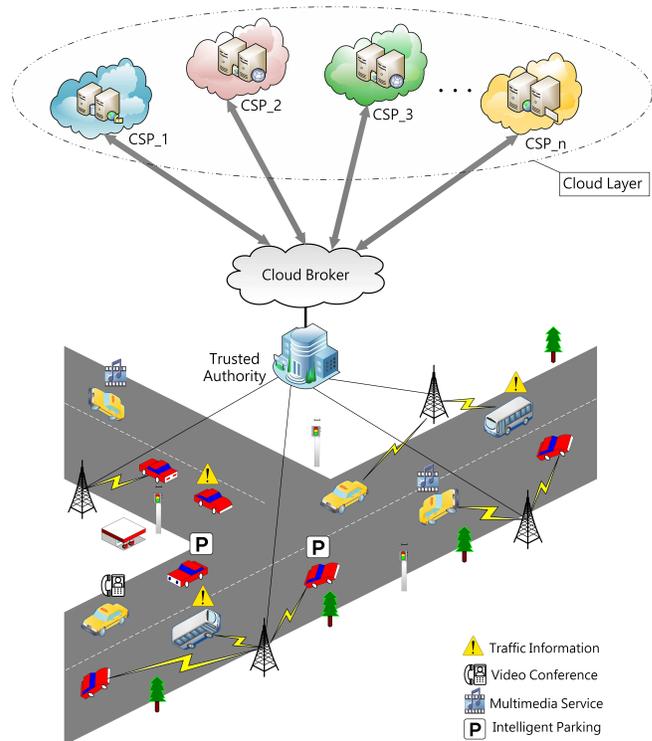


Fig. 1. The vehicular network model in a multi-cloud environment.

and base stations. The main functions of each entity and the system assumptions are described below.

- 1) **TA**: It is a widely accepted, reliable, independent and highly secure entity, which is undertaken by an Intelligent Transport System (ITS) department of government [39]. The TA equipped with tamper-resistant hardware has sufficient storage space and excellent computing capacity [40]. Its services are provided and underwritten by technical, legal, financial and/or structural means [41]. The TA is responsible for generating system parameters, and the registration of vehicles and CSPs. It is the only entity that can track the real identity of vehicles. It is assumed that the TA will never be compromised.
- 2) **CB**: It is governed by the TA and acts as an intermediary between vehicles and CSPs. The CB comprised of a partitioner, encryptor, decryptor, hash key generator, verifier and local database manager [42]. It is assumed that the CB will not be compromised. The CB is in charge of managing the application, performance and delivery of the cloud services, and assisting vehicle users in selecting the CSP that best suits their needs.
- 3) **CSP**: It provides vehicles with route recommendation, video-conferencing and driving assistance services, etc. Additionally, data in the tachograph can be stored in CSPs to alleviate the burden of content storage of vehicles, and prevent data loss due to the malfunction of the on-board equipment. The trusted computing platform (TCP) which is based on trusted platform module (TPM) is integrated into the cloud computing system [43]. And the TCP is used in authentication, confidentiality and integrity in cloud computing environment [44]. It is

assumed that the CSP is honest-but-curious, that is, it will faithfully enforce the scheme but is curious about vehicles' privacy data.

- 4) **Vehicle**: Vehicles are equipped with advanced on-board units (OBUs), which have good wireless communication capabilities, and limited computing power and storage space. The embedded TPM is a tamper-proof equipment that will not be broken. It is responsible for storing secret information related to vehicular communications and performing basic encryption and decryption operations [45]. Besides, the OBU possesses the functions for dedicated short-range communications (DSRC) communication, a wide area network connection, the electronic control units (ECU) connection, etc [46], [47].
- 5) **Base station**: It is deployed on both roadside as well as hotspots, and only responsible for relaying the messages in the vehicular networks. Since it does not involve any cryptographic operations, even if the base stations are compromised, no valuable information will be leaked. It is assumed that base stations are able to provide seamless coverage for vehicular communications with super-fast speed.

Note that, in view of the considerable amount of vehicles, the redundant TAs which have identical functionalities can be deployed based on the size of service area, to avoid becoming a single fault or a bottleneck [48]. Geographically distributed TAs collaborate for the network.

B. Security Objectives

The scheme is supposed to achieve the following security objectives:

- 1) **Anonymity**: In order to realize the privacy protection of vehicle's identity, the attackers cannot calculate its real identity from the messages. The real identity of vehicle keeps anonymous to all entities.
- 2) **Traceability**: When the vehicle or cloud service provider misbehaves, the TA can derive the real identity of these participating entities through the messages.
- 3) **Mutual authentication**: In order to ensure the reliability of the participants, the TA and CSPs as well as vehicles should be able to verify the legitimacy of each other.
- 4) **Session key agreement**: The vehicles and CSPs can negotiate a private session key for encrypting and decrypting the subsequent communications.
- 5) **Unlinkability**: No third party can link intercepted messages to the same vehicle.
- 6) **Forward security**: In order to achieve the secrecy of previous communication, it should be able to ensure that even if the adversary has cracked the current session key, it is impossible to get the session key used in previous communications through the intercepted messages.
- 7) **Resistance to common attacks**: The scheme should be able to withstand common types of attacks, such as replay attacks, off-line password guessing attacks, and impersonation attacks to ensure the security of the entire vehicular network.

IV. PROPOSED SCHEME

In this section, we give a detailed description of our scheme which consists of five phases. Firstly, the TA setups the whole system. The vehicles and CSPs then submit their registrations to the TA separately. Vehicle users must pass the third login phase successfully before they authenticate with CSPs. In the following authentication phases, we introduce the mutual authentication steps among vehicles, CSPs and TA in detail. Finally, it is the password change phase. The proposed scheme has the following advantages: 1) It has good scalability, specifically, the newly added CSPs can participate in the vehicular network service by registering with the TA only once; 2) during the whole mutual authentication and key agreement (AKA) phase, CSPs can not know the real identity of the vehicle, which realizes better privacy protection of vehicle's real identity; 3) it provides users with a quick and convenient password change phase; 4) no bilinear pairing operation is used, which reduces the time consumption of the whole system. Fig. 2 demonstrates our system framework. Notations are listed in Table I.

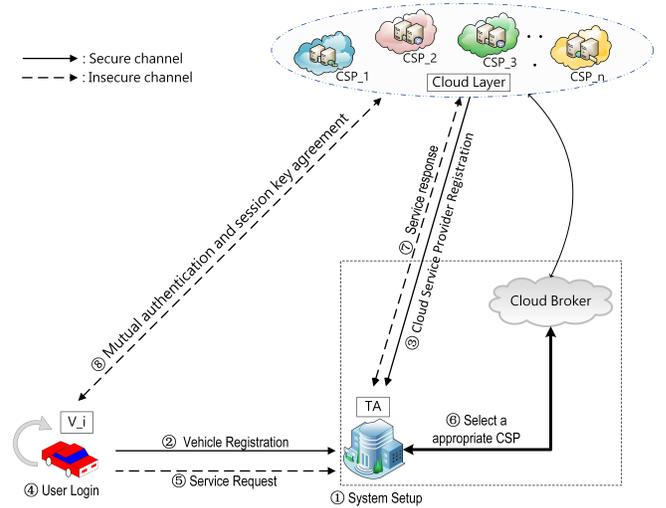


Fig. 2. Framework of the proposed scheme.

A. System Setup

Let F_p be the finite field over p , and p is a prime number denotes the size of finite field. The TA generates an additive cyclic group E , where $(a, b) \in F_p$ are the parameters of elliptic curve E . And P is the generator point of E with a prime order of q . O denotes infinity and $P \neq O$. Then the TA chooses two secure hash functions $h : \{0, 1\}^* \rightarrow \{0, 1\}^l$, $H : \{0, 1\}^* \rightarrow \{0, 1\}^l$, here l denotes the limit length of bit string. Next, the TA selects a random number $s \in F_p$ to compute its corresponding public key $P_{pub} = sP$. TA keeps s as its private key and publishes $\{P_{pub}, H, P, E\}$ as the public system parameters. Note that in order to further improve the robustness of the scheme, h will not be published and it only stored in the OBU of the registered vehicle.

TABLE I
NOTATIONS

Notations	Definitions
TA	Trusted authority
CB	Cloud broker
CSP_j	The j -th cloud service provider
V_i	The i -th vehicle
s	The private key of the TA
P_{pub}	The public key of the TA
UID_i	The real identity of user
ID_i	The real identity of V_i
PID_i	The pseudo identity of V_i generated by V_i itself
CID_i	The pseudo identity of V_i generated by the TA
ID_j	The real identity of CSP_j
PID_j	The pseudo identity of CSP_j generated by CSP_j itself
AID_j	The pseudo identity of CSP_j generated by the TA
PW_i	The password of V_i
M_i	A request message of V_i
tt_i	The latest timestamp
h, H	Two collision-free one-way hash functions
\parallel	Concatenation operation
\oplus	Exclusive-OR operation

B. Registration

In this phase, vehicles and cloud service providers submit their registration applications to the TA respectively.

• Vehicle Registration

Fig. 3 shows the interactions between the vehicle user and the TA during the vehicle registration phase. Details are described as follows.

- 1) The vehicle user selects a password PW_i and computes $EPW_i = h(UID_i \parallel PW_i)$, then V_i sends $\{ID_i, EPW_i\}$ to the TA through the secure channel. What the TA gets is the encrypted login password and the encrypted real identity of user; therefore, the adversary cannot successfully launch a stolen-verified attack.
- 2) TA computes $A_i = H(ID_i \parallel s)$, $B_i = A_i \oplus EPW_i$ and stores $\{B_i, P, H, h\}$ into the V_i . Meanwhile, the TA locally stores the real identity $\{ID_i\}$ of V_i .
- 3) V_i computes $C_i = h(UID_i \parallel ID_i \parallel PW_i)$, and then stores C_i into its on-board unit. At last, V_i is loaded by $\{B_i, C_i, P, H, h\}$.

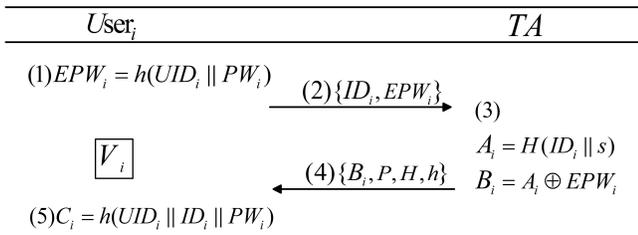


Fig. 3. Vehicle registration phase.

• Cloud Service Provider Registration

Fig. 4 shows the interactions between the cloud service provider and the TA during this registration phase. The following is a detailed description.

- 1) The cloud service provider CSP_j sends its identity ID_j to the TA via a secure channel.
- 2) The TA computes $Q_j = H(ID_j \parallel s)$ and sends it to the cloud service provider CSP_j .
- 3) The cloud service provider CSP_j keeps Q_j secretly.

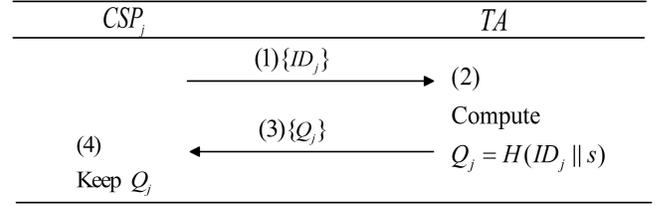


Fig. 4. Cloud service provider registration phase.

C. Login

Fig. 5 shows the user login process. As the first checkpoint, by the following two steps, V_i can verify the legitimacy of the user.

- 1) The user inputs UID_i , ID_i and PW_i to the V_i .
- 2) Vehicle V_i computes $C'_i = h(UID_i \parallel ID_i \parallel PW_i)$ and checks if C'_i equals to C_i . If the information entered by the user is right, this request will be permitted. Otherwise, this login request will be rejected.

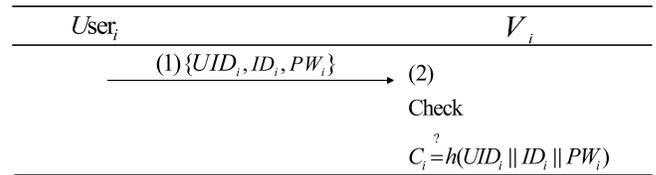


Fig. 5. User login phase.

D. Authentication and Session Key Agreement

As previously described, after successfully passing the login phase, V_i sends its request message M_i to the TA instead of broadcasting the message to CSPs. Then, the TA checks the legitimacy of V_i , if the vehicle is legal and has already registered, the cloud broker managed by the TA will recommend the most suitable CSP for V_i . Afterwards, V_i and CSP_j complete the authentication with the assistance of the TA. Additionally, a temporary session key is established to encrypt subsequent communications. The interaction processes in the AKA phase are shown in Fig. 6. The following are the detailed descriptions. It is worth noting that, about how to select appropriate cloud service provider is beyond the scope of this study, if you are interested in this issue, you can read the reference [49], [9], [50], and [16].

- 1) Vehicle V_i computes $EPW_i = h(UID_i \parallel PW_i)$, $A_i = B_i \oplus EPW_i$, and selects a random nonce $x \in Z_q^*$ to compute $X = xP$, $X^* = xP_{pub}$ and $\eta = H(ID_i \parallel M_i \parallel X \parallel X^* \parallel A_i)$, where $Z_q^* = \{0, 1, 2, \dots, q-1\}$. Then V_i generates a pseudo identity PID_i by itself, where $PID_i = ID_i \oplus H(X^* \parallel \eta)$ and tt_i is the

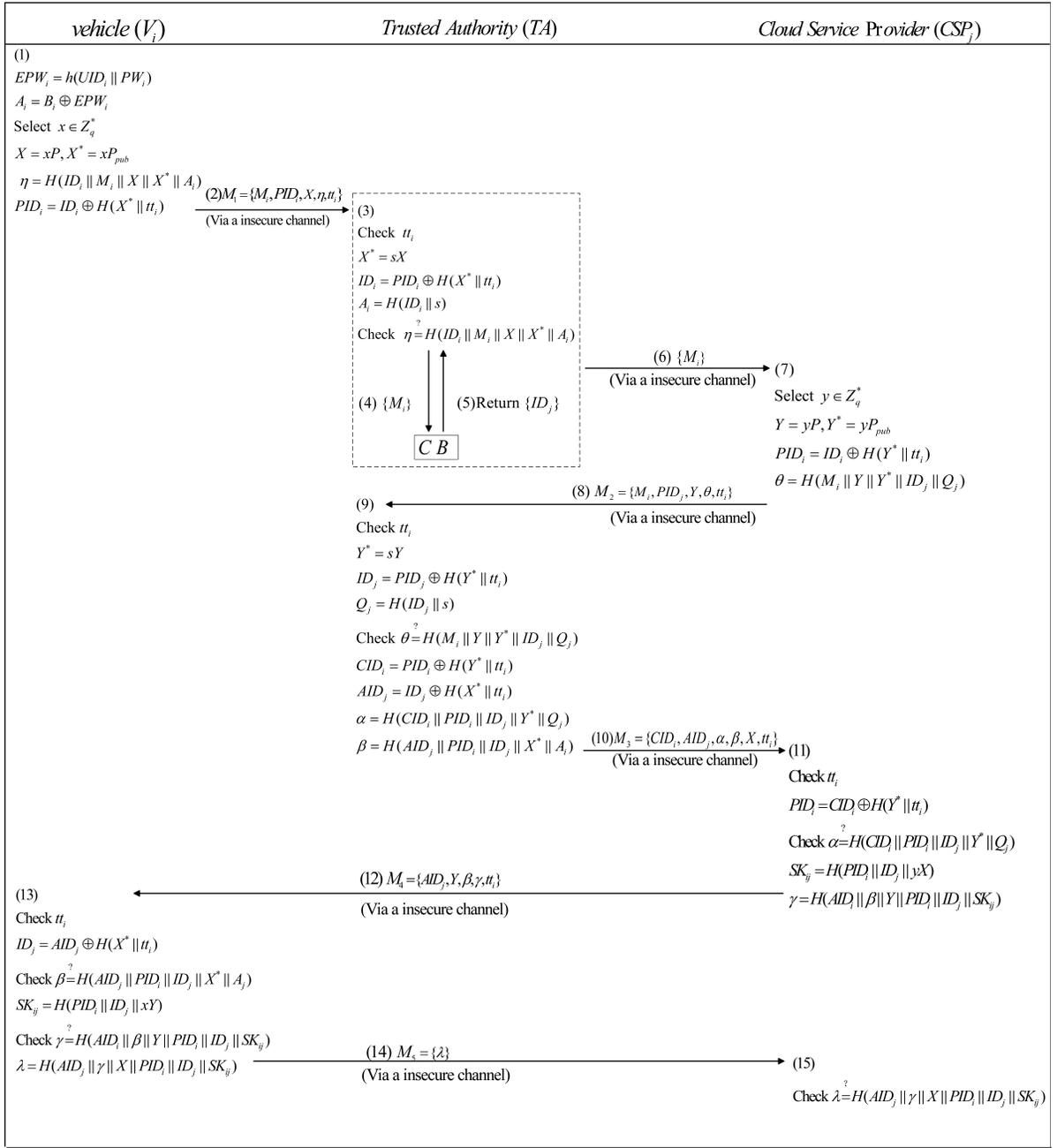


Fig. 6. Authentication and session key agreement phase of our scheme.

latest timestamp. Next, V_i send the message $M_1 = \{M_i, PID_i, X, \eta, tt_i\}$ to the TA.

- 2) Upon receiving M_1 from V_i , the TA first checks the timestamp of the message. If tt_i is expired, the TA would terminate the process. Otherwise, the TA computes $X^* = sX$ to get V_i 's real identity $ID_i = PID_i \oplus H(X^* || tt_i)$. If V_i is not in the revocation list, the TA computes $A_i = H(ID_i || s)$ and checks if η and $H(ID_i || M_i || X || X^* || A_i)$ are equal. If so, TA sends the requests message M_i to the cloud broker. Then the cloud broker finds suitable and reliable CSP_j according to the M_i , and returns the real identity of CSP_j to the TA.
- 3) The TA sends M_i to the cloud service provider CSP_j .

As a response, CSP_j selects a random nonce $y \in Z_q^*$ to compute $Y = yP$, $Y^* = yP_{pub}$ and $PID_j = ID_j \oplus H(Y^* || tt_i)$ upon receiving M_i from the TA. Here PID_j is the pseudo identity generated by CSP_j itself. Then CSP_j computes $\theta = H(M_i || Y || Y^* || ID_j || Q_j)$. Finally, CSP_j sends the message M_2 to the TA, where $M_2 = \{PID_j, Y, \theta, tt_i\}$.

- 4) After receiving M_2 from CSP_j , TA checks the validity of the timestamp at first. TA would terminate the process if tt_i is expired. If not, TA computes $Y^* = sY$ to get CSP_j 's real identity ID_j , where $ID_j = PID_j \oplus H(Y^* || tt_i)$. Next TA computes $Q_j = H(ID_j || s)$ and checks whether θ and $H(M_i || Y || Y^* || ID_j || Q_j)$ are e-

qual. If so, TA computes the authentication message: $CID_i = PID_i \oplus H(Y^* || tt_i)$, $AID_j = ID_j \oplus H(X^* || tt_i)$, $\alpha = H(CID_i || PID_i || ID_j || Y^* || Q_j)$, and $\beta = H(AID_j || PID_i || ID_j || X^* || A_i)$. Here, TA sends the encrypted pseudo identity of V_i to CSP_j for supporting the requirements of conditional privacy protection in the vehicular networks. Finally, TA sends $M_3 = \{CID_i, AID_j, \alpha, \beta, X, tt_i\}$ to the CSP_j .

- 5) CSP_j computes $PID_i = CID_i \oplus H(Y^* || tt_i)$ and verifies whether α and $H(CID_i || PID_i || ID_j || Y^* || Q_j)$ are equal. If yes, then CSP_j computes the session key $SK_{ij} = H(PID_i || ID_j || yX)$ and calculates $\gamma = H(AID_j || \beta || Y || PID_i || ID_j || SK_{ij})$. At last, CSP_j sends $M_4 = \{AID_j, Y, \beta, \gamma, tt_i\}$ to V_i .
- 6) Vehicle V_i computes $ID_j = AID_j \oplus H(X^* || tt_i)$ to get the real identity of CSP_j upon receiving the message M_4 . And then V_i checks if $\beta = H(AID_j || PID_i || ID_j || X^* || A_i)$ holds to verify whether the message indeed comes from the TA . If so, V_i computes $SK_{ij} = H(PID_i || ID_j || xY)$ to check whether γ is equal to $H(AID_j || \beta || Y || PID_i || ID_j || SK_{ij})$. If so, CSP_j is authenticated successfully. Consequently, V_i computes $\lambda = H(AID_j || \gamma || X || PID_i || ID_j || SK_{ij})$ and sends $M_5 = \{\lambda\}$ to the CSP_j .
- 7) Upon receiving the message M_5 , CSP_j calculates $H(AID_j || \gamma || X || PID_i || ID_j || SK_{ij})$ to verify whether it equals to λ . If yes, the session key SK_{ij} is assured for future secure communication between V_i and CSP_j .

Note that, when the vehicle and other CSPs perform the same steps in this phase, the negotiated session keys enable the vehicle to establish simultaneous links with multiple clouds.

E. Password Change

Fig. 7 shows our user-friendly password change phase which can be completed on the vehicle whenever users like. The following is a detailed description.

- 1) The user enters UID_i, ID_i, PW_i and the new password PW_i^* into V_i .
- 2) Vehicle V_i computes $C'_i = h(UID_i || ID_i || PW_i)$ and checks whether the equation $C'_i = C_i$ holds. If the information entered by the user is wrong, this process will be terminated. If not, then V_i performs $B_i^* = B_i \oplus h(UID_i || PW_i) \oplus h(UID_i || PW_i^*)$, and $C_i^* = h(UID_i || ID_i || PW_i^*)$ for changing PW_i into the new password PW_i^* .

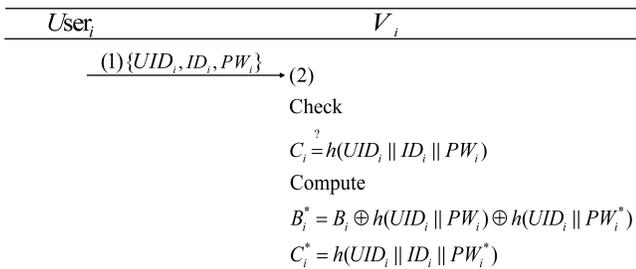


Fig. 7. Password change phase.

V. SECURITY ANALYSIS

In this section, we first introduce the preliminaries of ECDLP and ECDHP. Then, we define the security model and conduct the formal security proof to show that our scheme is indeed provably secure. Next, based on the safety requirements of the vehicular network, the security analysis is carried out in detail.

A. Preliminaries

The security of our scheme is based on the following elliptic curve computational problems, namely, Elliptic Curve Discrete Logarithm Problem (ECDLP) and Elliptic Curve Diffie-Hellman Problem (ECDHP).

- **ECDLP**: $y \in Z_q^*$, $Y = yP$, where $Y \in E_p$ and P is the generator of the E_p . Given $Y = yP$, it is not feasible to learn the integer y .
- **ECDHP**: $x, y \in Z_q^*$, and $X = xP, Y = yP$, where $X, Y \in E_p$ and P is the generator of the E_p . Given $X = xP$ and $Y = yP$, it is not feasible to compute the point $xyP \in E_p$.

B. Security Model

Assumed that three types of entities are in the authentication scheme Γ : TA which keeps the secret key s ; CSP_j which keeps the secret value D_i ; and V_i that keeps $\{PW_i, OBU_i, UID_i\}$. They all have multiple instances and can execute the authentication scheme Γ simultaneously. Each of them can be regarded as an oracle that usually has the following three states: *Accept*, which means the oracle receives a right message; *Reject*, which means the oracle receives a fault message; and \perp , which means no answer is output. As we mentioned in Section III. A, the base station does not participate in any encryption operation, and does not store any secret. That is to say, no one can obtain valuable information through the base station, so we do not consider it in this section.

Let V_i^α denote the α th instance of V_i , similarly, CSP_j^β and TA^γ denote the β th and the γ th instance of CSP_j and TA . We can say that V_i^α and CSP_j^β are partners, if either of them reach *Accept* state and a session key SK_{ij} is generated between them.

Definition 1 (Adversary's Capabilities): Adversary \mathcal{A} can query oracles as follows to learn the session key:

- **Execute – Oracle**: It simulates passive attacks. When \mathcal{A} invokes this query for accessing the honest authentication phase, it replies with $\{M_1, M_2, M_3, M_4, M_5\}$ to \mathcal{A} .
- **Send – Oracle**: It simulates active attacks. When \mathcal{A} invokes this query with a valid message m sending to V_i^α or CSP_j^β or TA^γ , this oracle will accept m and reply \mathcal{A} with corresponding answer according to Γ . Otherwise, the oracle sends *Reject* as a response.
- **Reveal – Oracle**: When \mathcal{A} invokes this query to learn the session key maintained by V_i^α , it answers with SK_{ij} only if V_i^α has turned into *Accept* state.
- **Corrupt – Oracle**: It allows \mathcal{A} to get access to the secret information of V_i^α .

- * $\pi = 0$: PW_i is obtained by \mathcal{A} via this inquiry.
- * $\pi = 1$: \mathcal{A} gets all the message stored in OBU_i via this query.
- * $\pi = 2$: \mathcal{A} learns the real identity UID_i of U_i via this query.
- *Corrupt-Oracle*: It only used to model forward secrecy, where \mathcal{A} can obtain all the secret values maintained by V_i^α , CSP_j^β and TA^γ .
- *Test-Oracle*: It tests the semantic security of the session key, and could be asked by \mathcal{A} at most once. If no session key has been generated or V_i^α 's (or CSP_j^β 's) instance is not fresh (see Definition 2), \perp will be the output. Otherwise, a bit b will be generated by this oracle. If $b = 1$, \mathcal{A} gets the real session key. If $b = 0$, it returns a random binary string as long as SK_{ij} to \mathcal{A} .

Definition 2 (Strong Forward Security-fresh): An instance V_i^α or CSP_j^β is strong forward security fresh unless any of the following cases appears:

- * A *Reveal* query sent by V_i^α or CSP_j^β appears.
- * *Corrupt* ($\pi = 0, 1, 2$) are all queried by \mathcal{A} .
- * The situation that V_i^α (CSP_j^β / TA^γ) has been sent *Corrupt* queries happens before *Test*.

Definition 3 (Semantic Security): The ability that \mathcal{A} can defeat the scheme Γ is defined as the probability of guessing the b accurately involved in the *Test-Oracle*. That is, the advantage of \mathcal{A} is: $Adv_\Gamma^{ake}(\mathcal{A}) = 2 * Pr[b = b'] - 1$. Γ is AKE-secure if $Adv_\Gamma^{ake}(\mathcal{A})$ is ignorably larger than $\max\{q_s(\frac{1}{|D|}, \frac{1}{2^{l_u}}, \varepsilon)\}$, where $|D|$ and q_s denote the length of password dictionary and the bound of *Send*-query respectively.

C. Formal Security Proof

Theorem 1: Let E_p be an elliptic curve group and D denote a uniformly distributed password dictionary with length is $|D|$. Γ represents our proposed scheme, and the advantage for adversary \mathcal{A} breaking Γ in upper-bound time t is:

$$Adv_\Gamma^{ake}(\mathcal{A}) \leq 2q_h((q_s + q_e)^2 + 1)Adv_A^{ECDH}(t + t_m(q_e + q_s)) + 2 \max\{q_s(\frac{1}{|D|}, \frac{1}{2^{l_u}}, \varepsilon)\} + \frac{2q_s + q_h^2 + q_u^2}{2^l} + \frac{(q_s + q_e)^2}{p} \quad (1)$$

Within the polynomial time t , \mathcal{A} can execute at most q_h Hash-queries, q_u Identity-queries, q_s Send-queries, and q_e Execute-queries. Where ε denotes the case "false positive", l is the length of hash values, t is the time cost of an elliptic curve point multiplication in an additional cyclic group G and l_u is the length of user's identity.

Proof: Six successive games $G_i(0 \leq i \leq 5)$ are conducted to confirm that our scheme is provably secure. Let $P[s_i]$ represent the probability that \mathcal{A} successfully guesses the value of b which exists in the *Test* query. Furthermore, Δ_i denotes the difference between $P[s_i]$ and $P[s_{i-1}]$. Specific proof as follows:

- *Game G_0* : G_0 is the real protocol under random oracle. According to the definition above, we can easily know: $Adv_\Gamma^{ake}(\mathcal{A}) = 2 \cdot P[S_0] - 1$. In order to prove $Adv_\Gamma^{ake}(\mathcal{A})$ is negligible, we perform the equation transformation:

$$Adv_\Gamma^{ake}(\mathcal{A}) = 2 \cdot P[S_0] - 1 - (2 \cdot P[S_0] - 2 \cdot P[S_5]) = 2 \cdot P[S_5] - 1 + 2 \cdot \sum_{i=1}^5 \Delta_i \quad (2)$$

- *Game G_1* : The hash oracle H maintains a hash list L_H , when \mathcal{A} invokes this query using a string str , it first exams whether the tuple $\langle str, H(str) \rangle$ already in L_H . If so, $H(str)$ will be returned. Otherwise, H returns \mathcal{A} with a random selected value $H(str)$ and stores $\langle str, H(str) \rangle$ into L_H . As the difference between G_0 and G_1 cannot be distinguished by \mathcal{A} , we have:

$$\Delta_1 = |P[S_1] - P[S_0]| = 0 \quad (3)$$

- *Game G_2* : G_2 simulates all the oracles in G_1 , and based on the birthday paradox there are two collisions:
 - * The maximum probability is $\frac{q_h^2 + q_H^2}{2^{l+1}}$ for the collision happened on two hash functions h and H .
 - * The maximum probability is $\frac{(q_s + q_e)^2}{2^p}$ for the collision happened on the nonce x and y .

If these two occurs, $P[S_2] = P[S_1]$ and \mathcal{A} wins the game. As the difference between G_1 and G_2 cannot be distinguished by \mathcal{A} , we have:

$$\Delta_2 = |P[S_2] - P[S_1]| \leq \frac{q_h^2 + q_H^2}{2^{l+1}} + \frac{(q_s + q_e)^2}{2^p} \quad (4)$$

- *Game G_3* : G_3 simulates all the oracle in G_2 . Here, the probability that \mathcal{A} fakes $\langle \eta, \theta, \alpha, \beta, \gamma, \lambda \rangle$ without random oracle be considered. As \mathcal{A} cannot tell the difference between G_2 and G_3 , therefore:

$$\Delta_3 = |P[S_3] - P[S_2]| \leq \frac{q_s}{2^l} \quad (5)$$

- *Game G_4* : G_4 simulates all the oracle in G_3 . The premise is that \mathcal{A} can get at most two factors, whereas \mathcal{A} can do nothing if he only own UID_i and PW_i . So, assume that \mathcal{A} has carried out the *Corrupt*($V_i, 1$) query. We argue that the ECDH problem could be solved if \mathcal{A} obtains a valid SK_{ij} . Following are three cases for \mathcal{A} getting other values:

- * \mathcal{A} executes q_s times *Corrupt*($V_i, 2$) queries for guessing PW_i . As there have $|D|$ passwords, the chance for right guessing PW_i is $\frac{q_s}{|D|}$.
- * \mathcal{A} executes *Corrupt*($V_i, 0$) query and chooses one of following two cases for cracking UID_i . Note that two cases cannot exist at the same time.

1. \mathcal{A} guesses UID_i with q_s times *Send* queries, and the probability is $\frac{q_s}{2^{l_u}}$.
2. \mathcal{A} provides his own UID_i and the probability of "false positive" is ε .

Obviously, the maximum probability of above is $q_s \cdot \max\{(\frac{1}{|D|}, \frac{1}{2^{l_u}}, \varepsilon)\}$.

- * In order to obtain the true SK_{ij} , where $SK_{ij} = H(PID_i || ID_j || xyP)$, \mathcal{A} is required to compute xyP using X , Y and P , where $X = xP$ and $Y = yP$. Hence, the advantage of \mathcal{A} is $Adv_{\mathcal{A}}^{ECDH}(t + t_m(q_e + q_s))$. Consequently, we have:

$$\Delta_4 = |P[S_4] - P[S_3]| \leq q_s \max\left\{\frac{1}{|D|}, \frac{1}{2^{l_u}}, \varepsilon\right\} + q_h \cdot Adv_{\mathcal{A}}^{ECDH}(t + t_m(q_e + q_s)) \quad (6)$$

- **Game G_5 :** According to the *Definition 2*, the *Corrupt – Oracle* must be queried after the *Test – Oracle*, that is, G_5 only affects old simulations. Like the third case in G_4 , suppose SK_{ij} could be found in the hash oracle, then the probability x and y in one session is $\frac{1}{(q_s + q_e)^2}$. And we can know:

$$\Delta_5 = |P[S_5] - P[S_4]| \leq q_h(q_s + q_e)^2 \cdot Adv_{\mathcal{A}}^{ECDH}(t + t_m(q_e + q_s)) \quad (7)$$

Finally, we get $P[S_5] = \frac{1}{2}$, therefore, \mathcal{A} can not win the game and the theorem is proved.

D. Security Analysis

- 1) **Anonymity:** The real identity ID_i of V_i is hidden in the PID_i , where $PID_i = ID_i \oplus H(X^* || tt_i)$ and $X^* = xP_{pub}$; therefore, others cannot get ID_i unless they are able to solve the ECDH problem.
- 2) **Traceability:** In order to prevent malicious vehicles and cloud service providers from misbehaving, TA can track the real identity of V_i and CSP_j by computing $ID_i = PID_i \oplus H(X^* || tt_i)$ and $ID_j = PID_j \oplus H(Y^* || tt_i)$. It should be emphasized that only TA can get the true identity of vehicles; consequently, our scheme meets the requirement of conditional privacy protection in vehicular networks.
- 3) **Mutual authentication:** By verifying whether $\langle \eta \rangle$ and $\langle \theta \rangle$ are valid, TA can authenticate the V_i and CSP_j accordingly. In the same way, V_i validates TA and CSP_i by verifying whether $\langle \beta \rangle$ and $\langle \gamma \rangle$ are effective. CSP_j can validate TA and V_i through the effectiveness of $\langle \alpha \rangle$ and $\langle \lambda \rangle$. Consequently, the proposed scheme can achieve mutual authentication between V_i , CSP_j and TA.
- 4) **Session key agreement:** CSP_j and V_i compute $SK_{ji} = H(PID_i || ID_j || yX)$ and $SK_{ij} = H(PID_i || ID_j || xY)$ independently. Afterwards, V_i and CSP_j confirm the validity of SK_{ij} for subsequent confidential communication by verifying the following equations: $\gamma = H(UID_j || \beta || Y || PID_i || ID_j || SK_{ij})$ and $\lambda = H(UID_j || \gamma || X || PID_i || ID_j || SK_{ij})$ respectively.
- 5) **Un-linkability:** Because the random numbers and timestamps are used in our scheme, the messages transmitted over the network are different. Additionally, the pseudo-ID of V_i and CSP_j are dynamically updated, therefore the adversary cannot distinguish whether two different messages originate from the same sender.
- 6) **Perfect forward secrecy:** Due to SK_{ij} equals to $H(PID_i || ID_j || xY)$ and $H(PID_i || ID_j || yX) = SK_{ji}$, therefore, only the adversary who is able to solve the

ECDH problem for getting the random numbers x and y , can generate a correct session key. That is, our scheme satisfies perfect forward secrecy.

- 7) **Resistant against ordinary attacks:** The proposed scheme protects against the following common attacks:
 - **Replay attack:** Given that timestamp tt_i is attached to the message, by checking the freshness of tt_i , participants could discover whether a replay has occurred.
 - **Offline password guessing attack:** During the registration, TA calculates $A_i = H(ID_i || s)$ with its secret key s . Additionally, PW_i could be easily changed by legal users, thus, in polynomial time no one could guess both s and PW_i correctly.
 - **Resistance impersonation of CSP:** Messages sent by CSP_j contain the Q_j , where Q_j equals to $H(ID_j || s)$. Because the system assumes that TA is completely trustworthy and unbreakable, therefore, any other entity can not be successfully forged as CSP_j as they do not know the private key s of TA.
 - **Resistance impersonation of vehicle:** In order to impersonate V_i for sending a legal request message, \mathcal{A} is required to know the correct A_i , where $A_i = H(ID_i || s)$. As we analysed before, the possibility for \mathcal{A} retrieving ID_i and s from the intercepted messages is negligible.

According to Table II, only our scheme can achieve more merits when compared with related schemes [51], [52], [53].

TABLE II
SECURITY COMPARISON

	[51]	[52]	[53]	Our scheme
Anonymity	*	*	×	*
Traceability	*	*	*	*
Un-linkability	*	×	*	*
Perfect forward secrecy	×	*	*	*
Replay attack	*	×	*	*
Impersonation attacks	×	*	*	*

* : The requirement is satisfied.

× : The requirement is not satisfied.

VI. PERFORMANCE EVALUATION

The dynamic nature of network topology and the limited computing power of OBU make it of great practical significance to realize fast and efficient authentication of vehicular networks. For proving the computation and communication overhead of our scheme can meet the requirements in the vehicular network, we compare it with three other novel authentication schemes. Moreover, we conduct simulation experiment in terms of packet loss ratio and average transmission delay to prove our scheme achieves better performance.

A. Computation Cost Analysis

In the scheme of [51], Liu *et al.* adopted bilinear pairings crypto-operations to design an efficient AKA scheme for V2V communications. In the schemes of Ying *et al.*'s [52], they proposed a lightweight and anonymous authentication based

on smart card protocol for secure vehicular networks. In [53], Jiang *et al.* proposed an integrated AKA framework for achieving mutual authentication and secure communications among users, vehicular cloud (VC), and conventional cloud (CC). Note that, both the scheme of Jiang *et al.*'s [53] and the proposed scheme are established on ECC, and Ying *et al.*'s [52] scheme involves modulo exponential operations.

The method of computation evaluation proposed in [2] is adopted in this study. We use MIRACL to get the execution time of cryptographic operations on the hardware platform which contains 8 gigabytes memory, an Intel I7-6700 processor, and runs Windows 7 operating system. Table III shows the details about the involved operations. Due to the time for performing XOR operation is negligible, we do not take this into account in computation time calculation.

Here, we introduce the analysis about Liu *et al.*'s scheme [51] and our scheme in detail only, as the specific computation cost analysis about [52] and [53] can be achieved similarly. From Table IV we can see the detailed computation cost of each entity. As mentioned before, Liu *et al.*'s scheme [51] adopted bilinear pairing crypto-operations. During the AKA phase, it requires OBU to execute two MapToPoint hash operations, one symmetric encryption operation, one bilinear pairing and one point addition operation about the bilinear pairing, that is, the execution time of OBU is $2T_{mtp} + T_s + T_{bp} + T_{ba} \approx 8.04$ ms. Meanwhile, the RSU is required to perform two MapToPoint hash operations, one bilinear pairing and two symmetric encryption operations, namely, the execution time of RSU is $2T_{mtp} + 2T_s + T_{bp} \approx 5.8364$ ms. As for TA, it needs to carry out three MapToPoint hash operations, one scale multiplication operation and one symmetric decryption operations; consequently, the execution time of TA is $3T_{mtp} + T_s + T_{bm} \approx 1.2676$ ms. Therefore, the total execution time in [51] for AKA is about 14.144 ms.

In our scheme, the computation time needed in vehicle is eight one-way hash function operations and three scale multiplication about the ECC, accordingly, the execution time is $3T_{em} + 8T_h \approx 0.9734$ ms. The base stations do not participate in the AKA phase. The CSP is required to perform seven one-way hash function operations and three scale multiplication about the ECC, that is, $3T_{em} + 7T_h \approx 0.9724$ ms. The computation time in TA is about 0.6536 ms which equals to ten times of one-way hash function operations and two scale multiplication about the ECC. Consequently, the total time needed in our scheme during AKA is about 2.5994 ms.

For demonstrating the major benefit of our scheme, in Fig. 8, we depict the comparison results from the aspects of time cost on vehicle and the total time cost during the whole AKA phase. Obviously, our scheme achieves better performance when compared with other related authentication schemes [51]-[53].

B. Communication Cost Analysis

As p is 20 bytes and \bar{p} is 64 bytes, the elements in G and G_1 are $20 \times 2 = 40$ bytes and $64 \times 2 = 128$ bytes respectively. Besides, without loss of generality, we set the size of timestamp be 4 bytes, the size of output of general hash

TABLE IV
COMPUTATION COST COMPARISON (MS)

	Vehicle	R/C/V	TA	Total
[51]	$2T_{mtp} + T_{bp} + T_{bpm} + T_s \approx 8.04$	$2T_{mtp} + T_{bp} + T_s \approx 5.5604$	$3T_{mtp} + T_{bpm} + T_s \approx 1.2656$	$7T_{mtp} + 2T_{bp} + 2T_{bpm} + 4T_s \approx 14.144$
[52]	$T_e + T_s + 6T_h \approx 6.296$	$T_h \approx 0.001$	$T_e + T_s + 5T_h \approx 6.295$	$2T_e + 2T_s + 12T_h \approx 12.592$
[53]	$3T_{ecm} + 9T_h + 4T_s \approx 2.0784$	(VC) : $3T_{ecm} + 4T_h + 5T_s \approx 2.3494$ (CC) : $3T_h + T_s \approx 0.279$	Null	$3T_{ecm} + 9T_h + 4T_s \approx 4.7068$
Our	$3T_{ecm} + 8T_h \approx 0.9734$	$3T_{ecm} + 7T_h \approx 0.9724$	$2T_{ecm} + 10T_h \approx 0.6536$	$8T_{ecm} + 25T_h \approx 2.5994$

R/C/V: It represents RSU, cloud or another vehicle.

Null: The entity is not considered in the system model of the scheme.

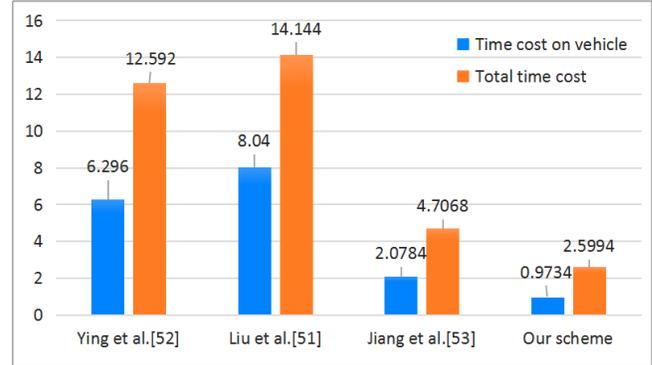


Fig. 8. Computation cost comparison.

function and symmetric encryption/decryption be 20 bytes. Here we only consider the length of messages during AKA phase only. Table V shows the detailed communication costs and the rounds in AKA.

TABLE V
COMMUNICATION COST

	Rounds in AKA	Length of messages
Liu's scheme [51]	5	2296 bytes
Ying's scheme [52]	5	216 bytes
Jiang's scheme [53]	6	444 bytes
Our scheme	5	416 bytes

We introduce the analysis about Liu *et al.*'s scheme [51] and the proposed scheme in detail only, due to the specific communication cost analysis about [52] and [53] can be computed in the same way. In Liu *et al.*'s scheme [51], there are five rounds in the AKA process, accordingly, the messages are from m_0 to m_4 , where $m_0 = \{AID_i, A_i, TS_i, r_iP, P_{pub}, query\}$, $m_1 = \{AID_j, A_j, TS_j, r_jP, P_{pub}\}$, $m_2 =$

TABLE III
EXECUTION TIME OF BASIC OPERATIONS (MS)

Symbol	Description	Format	Time (ms)
T_{bp}	Bilinear pairing operation	$\bar{e}(\bar{S}, \bar{T})$, where $\bar{S}, \bar{T} \in G_1$	5.086
T_{bpm}	Scale multiplication operation related to the bilinear pairing	$\bar{x} \cdot \bar{P}$, where $\bar{P} \in G_1, x \in Z_q^*$	0.694
T_{bpa}	Point addition operation related to the bilinear pairing	$\bar{S} + \bar{T}$, where $\bar{S}, \bar{T} \in G_1$	0.0018
T_{mtp}	MapToPoint hash operation related to the bilinear pairing	$H_1 : \{0, 1\}^* \rightarrow G_1$	0.0992
T_{ecm}	Scale multiplication operation related to the ECC	$x \cdot P$, where $P \in G$ and $x \in Z_q^*$	0.3218
T_{eca}	Point addition operation related to the ECC	$S + T$, where $S, T \in G$	0.0024
T_h	One-way hash function operation	$h : \{0, 1\}^* \rightarrow \{0, 1\}^l$	0.001
T_e	Modular exponentiation operation	$g^x \bmod n$	6.014
T_s	Symmetric encryption/decryption operation	AES-CBC	0.276

$\{C, AID_i, AID_j, MAC, TS_r, P_r\}$, $m_3 = \{AID_i, AID_j, TD_i, TD_j, E_{xi}(q^{r_i r_t}), E_{xj}(q^{r_j r_t}), TS_t, \sigma, M\}$, and $m_4 = \{SK_{i-j}, data\}$. Owing to $\langle AID_i, AID_j, r_i P, r_j P, P_{pub}, P_r, MAC, \sigma, M, SK_{i-j} \rangle \in G_1$ $\langle A_i, A_j, C \rangle$ are the outputs of symmetric encryption, $\langle TD_i, TD_j \rangle$ belong to the identity database, $\langle E_{xi}(q^{r_i r_t}), E_{xj}(q^{r_j r_t}) \rangle$ are the results of modular exponential operation, and $\langle TS_i, TS_j, TS_r, TS_t \rangle$ denote the timestamp, the total communication cost in Liu *et al.*'s scheme [51] is $128 \times 17 + 20 \times 5 + 5 \times 4 = 2296$ bytes.

Next is the analysis of our scheme. It also contains five rounds in the AKA process and the messages are from m_1 to m_5 , where $M_1 = \{M_i, PID_i, X, \eta, tt_i\}$, $M_2 = \{PID_j, Y, \theta, tt_i\}$, $M_3 = \{CID_i, AID_j, \alpha, \beta, X, tt_i\}$, $M_4 = \{AID_j, Y, \beta, \gamma, tt_i\}$ and $M_5 = \{\lambda\}$. Due to $\langle X, Y \rangle \in G$, $\langle PID_i, PID_j, \eta, \theta, \alpha, \beta, \gamma, \lambda, CID_i, AID_j \rangle$ are the results of one-way hash operation, and tt_i denotes the latest timestamp, consequently, the total communication overhead is $40 \times 4 + 20 \times 12 + 4 \times 4 = 416$ bytes.

According to the above analysis combined with Table V as well as the Fig. 9, we can draw the conclusion that the overall communication cost of our scheme is suitable for applications involving vehicular networks.

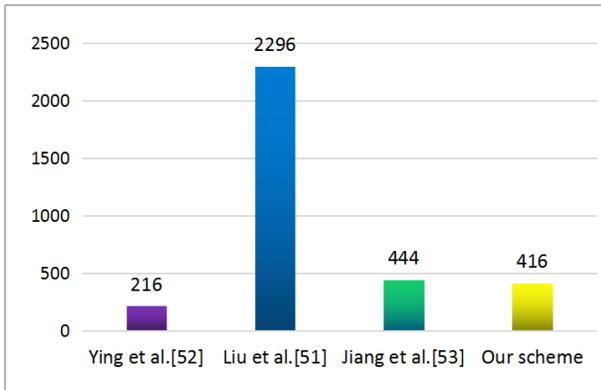


Fig. 9. Communication cost comparison.

C. Packet Loss Ratio and Average Transmission Delay

In this section, we compare our scheme with the other three schemes [51], [52], [53] on packet loss ratio and average

time delay. The simulation platform is composed of Omnet++, Sumo, Veins and Miracl [54]. Among them, Omnet++ is an extensible, modular C++ simulation library and build network simulators supporting the simulation for wired network and wireless mobile ad hoc network. Sumo is an open road traffic simulation package for handling large road networks. Veins is the middleware linking the first two modules. Table VI lists the relevant parameters used in the simulation experiment.

TABLE VI
SIMULATION PARAMETERS

Parameters	Value
Simulation area	$2500 \times 2500(m^2)$
Data Transmission Rate	24 Mbps
Transmission Power	40 mW
Sensitivity	-89 dBm

1) *Packet Loss Ratio*: In equation (8), the packet loss ratio P_L is defined. The so-called packet loss ratio refers to the percentage of lost messages in the total number of messages sent by vehicles, where $Avg(\cdot)$ refers to a averaging function. n represents the number of vehicles. Num_r^i denotes the number of messages received from vehicle V_i . And Num_l^i refers to the number of lost messages.

$$P_L = Avg(\sum_{i=1}^n Num_r^i (Num_r^i + Num_l^i)^{-1}) \quad (8)$$

We compare our scheme with related schemes [51], [52], and [53] in terms of packet loss ratio. The fixed size of packages sent by vehicles is 400 KB. Fig. 10 shows the relationship between packet loss ratio and vehicle's speed, where the x-axis represents the maximum speed of the vehicle. From Fig. 10, we can see that the trend of packet loss ratio of [52] and [53] is very close, and our scheme achieves the minimum packet loss ratio.

2) *Average Transmission Delay*: We define the average transmission delay T_D of the message between the receiver and the sender in equation (9). Where n represents the number of vehicles. N^j refers to the number of messages received from the vehicle V_j . And T_s^j, T_r^j represent the time at which the message is sent and the time at which the message is received, respectively. It goes without saying that $T_r^j - T_s^j$ corresponds to the time it takes for the message to perform a one-way transmission between the receiver and the sender.

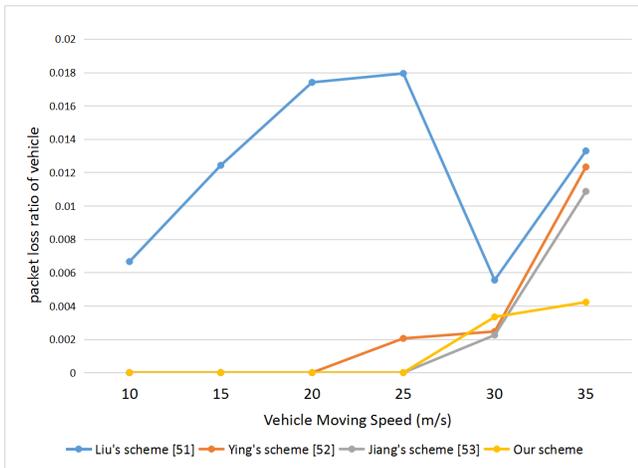


Fig. 10. The relationship between packet loss ratio and vehicle's moving speed

$$T_D = Avg(\sum_{i=1}^n Avg(\sum_{j=1}^{N_j} (T_r^j - T_s^j))) \quad (9)$$

Fig. 11 shows the average packet delay between our scheme and [51], [52], and [53]. Identically, we set the fixed package size be 400 KB. From Fig. 11, we can see that the average packet delay of different schemes tends to be stable at different vehicle speeds, while our scheme achieves the minimum average transmission packet delay, that is to say, our scheme achieves better performance.

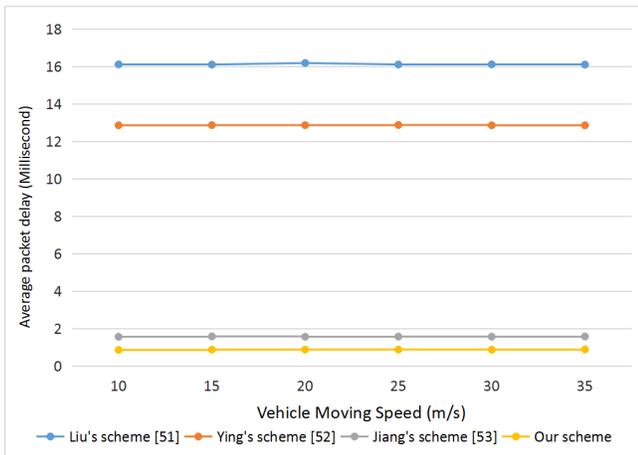


Fig. 11. The relationship between average packet delay and vehicle's moving speed

VII. CONCLUSION

In this study, we proposed our novel insights on the vehicular network authentication over a multi-cloud environment. The main objective of this scheme is to propose a vehicular network anonymous authentication scheme that can be practically applied to a multi-cloud environment. The CSPs need to register with the TA only once to participate in the network services; consequently, our scheme demonstrates good scalability. As the TA is responsible for the registration of vehicles, the

CSPs do not need to store the considerable amount of redundant vehicles registration information. Moreover, the hassle of public key management is reduced for vehicle users. A detailed security analysis as well as the calculation and communication cost comparisons with related schemes established that our scheme can achieve the security objectives in the vehicular network with lower time consumption. In the future, we will apply reputation mechanism in the model of this scheme and design a multi-level feedback mechanism to evaluate the CSPs to provide improved cloud services for vehicles.

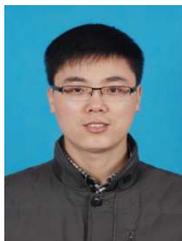
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